



CHARACTERIZATION OF LIGHTLIKE HYPERSURFACES IN THE LORENTZ-MINKOWSKI SPACE $\mathbb{R}_1^4$ WITH ITS STRUCTURE EQUATIONS

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ABSTRACT. In this paper, we introduce the notion of structure equations on lightlike hypersurfaces and we give a characterization of lightlike hypersurfaces in the Lorentz-Minkowski space $\mathbb{R}_1^4$ satisfies the equation $\Delta H = \lambda H$, where H and Δ are the mean curvature of M and Laplace operator respectively.

1. INTRODUCTION

Theory of hypersurfaces is one of the fundamental theories of submanifolds. In semi-Riemannian manifold, there are three types of hypersurfaces : Riemannian; semi-Riemannian and lightlike. The geometry of lightlike hypersurfaces is different and rather difficult since its normal vector bundle intersects with the tangent bundle. Duggal and Bejancu [7] published in 1996 a book on general theory of lightlike submanifolds of semi-Riemannian manifolds. They introduced a non-degenerate screen distribution to construct a lightlike transversal vector bundle which is non-intersecting to its lightlike tangent bundle. We know that the shape operator plays a key role in the study geometry of submanifolds. In this paper, we will study a class of lightlike hypersurfaces of a Lorentz-Minkowski space $\mathbb{R}_1^4$, whose shape operators are conformal to shape operators of their corresponding screen distributions.

The main purpose of this paper is to introduce the structure equations and give a characterization of lightlike hypersurfaces satisfying the equation $\Delta H = \lambda H$. In section 2, we give useful preliminaries for study the geometry of lightlike hypersurfaces. In section 3, we will give the structure equations on the lightlike hypersurfaces of the Lorentz-Minkowski space $\mathbb{R}_1^4$.

Let $x : M \longrightarrow \mathbb{R}_1^4$ be an isometric immersion of a lightlike hypersurface into the Lorentz-Minkowski space $\mathbb{R}_1^4$. Denoted by H and Δ the mean curvature of M and Laplace operator respectively. The equation $\Delta H = \lambda H$, for some real constant λ , is a natural generalization of the biharmonic equation $\Delta H = 0$. In the case of a non-degenerate hypersurface, Ferrandez and Lucas originate in [8] the study of hypersurfaces in $\mathbb{R}_1^3$

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satisfying $\Delta H = \lambda H$, where they proved that the hypersurfaces in $\mathbb{R}_1^3$ have constant mean curvature and classified such hypersurfaces. Moreover, A.Arvanitoyeorgos and G.Kaimakamis made a conjecture in [1] saying that any hypersurface satisfying $\Delta H = \lambda H$ in pseudo-Euclidean space $\mathbb{E}_s^{n+1}$ has constant mean curvature, A.Arvanitoyeorgos and Al. proved in [2] that this conjecture is true for hypersurfaces M_r^3 of $\mathbb{E}_s^4$ whose shape operator is diagonalizable. As a matter of course, it is interesting to study this conjecture for the lightlike hypersurfaces of $\mathbb{R}_1^4$. In this paper, we will give some conditions on the screen distribution for which the lightlike hypersurface satisfy the equation $\Delta H = \lambda H$ and has constant mean curvature in section 4. Finally, we take the lightlike cone of $\mathbb{R}_1^3$ as an application example of a lightlike hypersurface of $\mathbb{R}_1^4$ satisfying the equation $\Delta H = \lambda H$ in section 5.

2. PRELIMINARIES ON LIGHTLIKE HYPERSURFACES

2.1. Geometry of lightlike hypersurface. Let M be a hypersurface of a $(m+2)$ -dimensional semi-Riemannian manifold $(\bar{M}, \bar{g})$. Denote by g the tensor field induced by $\bar{g}$ on M . We say that M is a lightlike hypersurface if $\text{rank}(g) = m$. Thus the normal vector bundle $TM^\perp$ intersects the tangent bundle along a nonzero distribution which called the radical distribution of M and denoted by $\text{Rad}(TM)$ where

$$\text{Rad}(TM) : p \mapsto \text{Rad}(T_p M) = T_p M \cap T_p M^\perp. \quad (2.1)$$

A non-degenerate vector bundle complementary to $TM^\perp$ on M is called a screen distribution denoted by $S(TM)$. A lightlike hypersurface endowed with a screen distribution is denoted by the triple $(M, g, S(TM))$.

The following result has an important role in the study of the geometry of the lightlike hypersurfaces.

Theorem 2.1. ([7]) *Let $(M, g, S(TM))$ be a lightlike hypersurface of $(\bar{M}, \bar{g})$. Then there exists a unique vector bundle $\text{tr}(TM)$ of rank 1 over M , such that for any non zero section ξ of $TM^\perp$ on a coordinate neighborhood $\mathcal{U} \subset M$, there exists a unique section N of $\text{tr}(TM)$ on $\mathcal{U}$ satisfying*

$$\bar{g}(N, \xi) = 1 \text{ and } \bar{g}(N, N) = \bar{g}(N, W) = 0, \forall W \in \Gamma(S(TM)). \quad (2.2)$$

By this theorem we may write the following decomposition

$$T\bar{M}|_M = S(TM) \perp (TM^\perp \oplus \text{tr}(TM)) = TM \oplus \text{tr}(TM), \quad (2.3)$$

where $\perp$ denotes an orthogonal direct sum and $\oplus$ a direct sum.

Let $(M, g, S(TM))$ be a lightlike hypersurface of a semi-Riemannian manifold $(\bar{M}, \bar{g})$, $\bar{\nabla}$ be the Levi-Civita connexion of $\bar{M}$ and ∇ the induced connexion on (M, g) . Gauss and Weigarten formulas provide the following relations (for details see [7])

$$\bar{\nabla}_X Y = \nabla_X Y + h(X, Y), \quad (2.4)$$

$$\bar{\nabla}_X V = -A_V X + \nabla_X^t V, \quad (2.5)$$

for all $X, Y \in \Gamma(TM)$ and $V \in \text{tr}(TM)$, where $\nabla_X Y$ and $A_V X$ belong to $\Gamma(TM)$ while h is a $\Gamma(\text{tr}(TM))$ -valued symmetric $C^\infty(M)$ -bilinear form on $\Gamma(TM)$ and ∇^t is a linear connection on $\text{tr}(TM)$ which is a torsion-free.

Define a $C^\infty(M)$ -bilinear form B and a 1-form τ on the coordinate neighborhood $\mathcal{U} \subset M$ by

$$B(X, Y) = \bar{g}(h(X, Y), \xi), \quad (2.6)$$

$$\tau(X) = \bar{g}(\nabla_X^t N, \xi), \quad (2.7)$$

for all $X, Y \in \Gamma(TM|_{\mathcal{U}})$. Thus, equations (2.4) and (2.5) become on $\mathcal{U}$

$$\bar{\nabla}_X Y = \nabla_X Y + B(X, Y)N, \quad (2.8)$$

$$\bar{\nabla}_X V = -A_V X + \tau(X)N, \quad (2.9)$$

respectively. B is called the local second fundamental form and does not depend on the choice of the screen distribution, and satisfies

$$B(X, \xi) = 0, \quad (2.10)$$

for all $X \in \Gamma(TM|_{\mathcal{U}})$. Let P be the projection morphism of TM to $S(TM)$ with respect to the decomposition (2.3). Then

$$\nabla_X PY = \overset{*}{\nabla}_X PY + \overset{*}{h}(X, PY), \quad (2.11)$$

$$\nabla_X U = -\overset{*}{A}_U X + \overset{*}{\nabla}_X^t U, \quad (2.12)$$

where $\overset{*}{\nabla}_X PY$ and $\overset{*}{A}_U X$ belong to $\Gamma(S(TM))$, $\overset{*}{\nabla}$ and $\overset{*}{\nabla}^t$ are linear connections on $\Gamma(S(TM))$ and $\Gamma(TM^\perp)$ respectively, $\overset{*}{h}$ is a $C^\infty(M)$ -bilinear form on $\Gamma(TM) \times \Gamma(S(TM))$, $\overset{*}{A}_U$ is a $\Gamma(S(TM))$ -valued $C^\infty(M)$ -linear operator on $\Gamma(S(TM))$. $\overset{*}{h}$ and $\overset{*}{A}_U$ are the second fundamental form and the shape operator of the screen distribution $S(TM)$ respectively. On $\mathcal{U}$ define the following relations

$$C(X, PY) = \bar{g}(\overset{*}{h}(X, PY), N), \quad (2.13)$$

$$\epsilon(X) = \bar{g}(\overset{*}{\nabla}_X^t \xi, N). \quad (2.14)$$

It is easy to show that $\epsilon(X) = -\tau(X)$. Thus, equations (2.11) et (2.12) become

$$\nabla_X PY = \overset{*}{\nabla}_X PY + C(X, PY)\xi, \quad (2.15)$$

$$\nabla_X U = -\overset{*}{A}_\xi X - \tau(X)\xi, \quad (2.16)$$

respectively. The linear connection $\overset{*}{\nabla}$ is a metric connection on $\Gamma(S(TM))$. In general, the induced connection ∇ on M is not metric and we have

$$(\nabla_X g)(Y, Z) = B(X, Y)\eta(Z) + B(X, Z)\eta(Y), \quad (2.17)$$

for all $X, Y \in \Gamma(TM|_{\mathcal{U}})$, where

$$\eta(X) = \bar{g}(X, N), \text{ for all } X \in \Gamma(TM|_{\mathcal{U}}). \quad (2.18)$$

It is easy to verify that for all $X, Y \in \Gamma(TM|_{\mathcal{U}})$

$$B(X, Y) = g(\overset{*}{A}_\xi X, Y), \quad g(A_N X, N) = 0, \quad (2.19)$$

$$C(X, PY) = g(A_N X, Y), \quad \overset{*}{A}_\xi \xi = 0, \quad (2.20)$$

Let $\bar{R}$ et R the curvature tensor associated with $\bar{\nabla}$ et ∇ . Then we have the following relations [7]

$$\bar{R}(X, Y)Z = R(X, Y)Z + A_{h(X, Z)}Y - A_{h(Y, Z)}X + (\nabla_X h)(Y, Z) - (\nabla_Y h)(X, Z), \quad (2.21)$$

$$\bar{g}(\bar{R}(X, Y)\xi, N) = C(Y, A_\xi^* X) - C(X, A_\xi^* Y) - 2d\tau(X, Y). \quad (2.22)$$

Next, we give some characteristics of the lightlike hypersurfaces.

2.2. Quasi-conformal screen Lightlike hypersurfaces.

Definition 2.1. ([10]) A lightlike hypersurface $(M, g, S(TM))$ of a semi-Riemannian manifold is locally screen quasi-conformal if the shape operators A_N and A_ξ^* of M and $S(TM)$ respectively satisfy

$$A_N = \varphi A_\xi^* + \psi P, \quad (2.23)$$

where φ and ψ are non-vanishing smooth function on a neighborhood $\mathcal{U}$ in M and P be the natural projection morphism of TM to $S(TM)$. If the above property holds everywhere on M , we say that $(M, g, S(TM))$ is globally screen quasi-conformal.

It easy to see that (2.23) is equivalent to

$$C(X, PY) = \varphi B(X, PY) + \psi g(X, PY) \quad (2.24)$$

for any $X, Y \in \Gamma(TM)$. If $\psi \equiv 0$, we have :

Definition 2.2. ([4]) A lightlike hypersurface $(M, g, S(TM))$ of a semi-Riemannian manifold is said to be locally screen (resp. globally) conformal if on any coordinate neighborhood $\mathcal{U}$ (resp. $\mathcal{U} = M$), the shape operators A_N and A_ξ^* satisfy

$$A_N = \varphi A_\xi^*, \quad (2.25)$$

where φ is a non-vanishing smooth function on $\mathcal{U}$ (resp. $\mathcal{U} = M$). In particular, M is screen homothetic if φ is non-zero constant.

Next, we show how to induce a Riemannian metric on a lightlike hypersurface (see for details [9]).

Definition 2.3. Let M be lightlike hypersurface in a Lorentzian manifold. A rigging for M is a vector field ζ defined on some open set containing M such that $\zeta_p \notin T_p M$ for each $p \in M$.

Given a rigging ζ in a neighborhood of M in $(\bar{M}, \bar{g})$, denoted by α the 1-form $\bar{g}$ -metrically equivalent to ζ , i.e. $\alpha = \bar{g}(\zeta, \cdot)$. Take $\omega = i^* \alpha$, being $i : M \hookrightarrow \bar{M}$ the canonical inclusion. Consider the tensors

$$\check{g} = g + \alpha \otimes \alpha \text{ and } \tilde{g} = i^* \check{g} = i^* g + \omega \otimes \omega. \quad (2.26)$$

It is easy to show that $\tilde{g}$ defines a Riemannian metric on the hypersurface M . The rigged vector field of ζ is the $\tilde{g}$ -metrically equivalent vector field to the 1-form ω and it is denoted by $\check{\zeta}$. In fact, the rigged vector field $\check{\zeta}$ is the unique lightlike vector field in M , such that $\tilde{g}(\check{\zeta}, \check{\zeta}) = 1$. Moreover $\check{\zeta}$ is $\tilde{g}$ -unitary. We can consider the screen distribution given by $TM \cap \check{\zeta}^\perp$ which denoted by $\mathcal{S}(\check{\zeta})$ and it is $\tilde{g}$ -orthogonal subspace to $\check{\zeta}$. The corresponding lightlike transverse vector field to $\mathcal{S}(\check{\zeta})$ is as follow

$$N = \check{\zeta} - \frac{1}{2} \tilde{g}(\check{\zeta}, \check{\zeta}) \check{\zeta}. \quad (2.27)$$

3. STRUCTURE EQUATIONS ON LIGHTLIKE HYPERSURFACES

Let $(M, g, S(TM))$ be a lightlike hypersurface of Lorentz-Minkowski space $\mathbb{R}_1^4$, ∇ and $\bar{\nabla}$ be connection on M and Levi-Civita connection of $\mathbb{R}_1^4$ respectively. Consider $\{E_1, E_2\}$ an orthonormal frame field of $S(TM)$ and set $\{E_1, E_2, \xi\} = \{E_1, E_2, E_3\}$ an orthonormal basis relative to the metric $\tilde{g}$.

Put $\omega^i = \tilde{g}(E_i, \cdot)$, for $i = 1, 2, 3$. Then $\{\omega^i\}_{i=1,2,3}$ forms the dual basis of $\{E_i\}_{i=1,2,3}$. We have $X = \sum_{i=1}^3 \tilde{g}(X, E_i)E_i = \sum_{i=1}^3 \omega^i(X)E_i$ for any $X \in \Gamma(TM)$. The connection forms are defined as follow :

$$\omega_i^j(X) = \tilde{g}(\nabla_X E_i, E_j), \quad 1 \leq i, j \leq 3, \quad (3.1)$$

with

$$\nabla_X E_i = \sum_j \tilde{g}(\nabla_X E_i, E_j)E_j = \sum_j \omega_i^j(X)E_j. \quad (3.2)$$

We have the following result, which gives the structural equations on the lightlike hypersurfaces.

Proposition 3.1. *Let $(M, g, S(TM))$ be a lightlike hypersurface of Lorentz-Minkowski space $\mathbb{R}_1^4$, ∇ and $\bar{\nabla}$ be connection on M and Levi-Civita connection of $\mathbb{R}_1^4$ respectively, $\{\omega^i\}_{i=1,2,3}$ the dual basis of $\{E_i\}_{i=1,2,3}$ and $\{\omega_i^j\}_{1 \leq i, j \leq 3}$ the connection forms. We have the following result*

i)

$$\omega_i^j(X) + \omega_j^i(X) = \begin{cases} 0 & \text{if } i, j \in \{1, 2\} \\ -2\tau(X) & \text{if } i = j = 3 \\ g(A_N X - \bar{A}_\xi^* X, E_i) & \text{if } i \in \{1, 2\} \text{ and } j = 3. \end{cases}$$

ii)

$$d\omega^i(E_j, E_k) = \omega_j^i(E_k) - \omega_k^i(E_j).$$

iii)

$$\begin{aligned} d\omega_i^j(E_k, E_l) = & B(E_k, \nabla_{E_l} E_i) \omega(E_j) + B(E_k, E_j) \omega_i^3(E_l) - B(E_l, \nabla_{E_k} E_i) \omega(E_j) \\ & - B(E_l, E_j) \omega_i^3(E_k) + B(E_l, E_i) g(A_N E_k, E_j) \\ & - B(E_k, E_i) g(A_N E_l, E_j) - \sum_{t=1}^2 \omega_i^t \wedge \omega_j^t(E_k, E_l) \\ & + \{E_k(\omega_i^3(E_l)) - E_l(\omega_i^3(E_k)) - \omega_i^3([E_k, E_l])\} \omega(E_j). \end{aligned}$$

Proof. i) For $i, j \in \{1, 2, 3\}$, we have $\tilde{g}(E_i, E_j) = \delta_{ij}$. Then for all $X \in \Gamma(TM)$, $X \cdot \tilde{g}(E_i, E_j) = 0$

$$\Leftrightarrow (\nabla_X \tilde{g})(E_i, E_j) + \tilde{g}(\nabla_X E_i, E_j) + \tilde{g}(E_i, \nabla_X E_j) = 0$$

$$\Leftrightarrow (\nabla_X \tilde{g})(E_i, E_j) + \omega_i^j(X) + \omega_j^i(X) = 0$$

$$\Rightarrow \omega_i^j(X) + \omega_j^i(X) = -(\nabla_X \tilde{g})(E_i, E_j).$$

and for all $Y, Z \in \Gamma(TM)$, we have :

$$(\nabla_X \tilde{g})(Y, Z) = X \cdot \tilde{g}(Y, Z) - \tilde{g}(\nabla_X Y, Z) - \tilde{g}(Y, \nabla_X Z). \quad (3.3)$$

But $\tilde{g} = i^*g + \omega \otimes \omega$ with $\omega = \tilde{g}(\xi, \cdot)$.

Thus $\tilde{g}(Y, Z) = g(Y, Z) + \omega(Y)\omega(Z)$. And $X.\tilde{g}(Y, Z) = X.g(Y, Z) + X(\omega(Y))\omega(Z) + \omega(Y)X(\omega(Z))$.

$$\tilde{g}(\nabla_X Y, Z) = g(\nabla_X Y, Z) + \omega(\nabla_X Y)\omega(Z)$$

$$\tilde{g}(Y, \nabla_X Z) = g(Y, \nabla_X Z) + \omega(Y)\omega(\nabla_X Z).$$

Then, we have:

$$\begin{aligned} (\nabla_X \tilde{g})(Y, Z) &= (\nabla_X g)(Y, Z) + \{X(\omega(Y)) - \omega(\nabla_X Y)\}\omega(Z) \\ &\quad + \{X(\omega(Z)) - \omega(\nabla_X Z)\}\omega(Y). \end{aligned}$$

But $(\nabla_X g) = B(X, Y)\eta(Z) + B(X, Z)\eta(Y)$ where $\eta(Y) = g(N, Y)$ and since $N = \xi - \frac{1}{2}g(\xi, \xi)\xi$ then $\eta(X) = \omega(X)$, $\forall X \in \Gamma(TM)$. So $(\nabla_X g) = B(X, Y)\omega(Z) + B(X, Z)\omega(Y)$. Therefore,

$$\begin{aligned} (\nabla_X \tilde{g})(Y, Z) &= B(X, Y)\omega(Z) + B(X, Z)\omega(Y) + \{X(\omega(Y)) - \omega(\nabla_X Y)\}\omega(Z) \\ &\quad + \{X(\omega(Z)) - \omega(\nabla_X Z)\}\omega(Y). \end{aligned}$$

Assume, $Y = E_i, Z = E_j$, for any $i, j \in \{1, 2, 3\}$, we obtain,

$$\begin{aligned} (\nabla_X \tilde{g})(E_i, E_j) &= B(X, E_i)\omega(E_j) + B(X, E_j)\omega(E_i) + \{X(\omega(E_i)) - \omega(\nabla_X E_i)\}\omega(E_j) \\ &\quad + \{X(\omega(E_j)) - \omega(\nabla_X E_j)\}\omega(E_i). \end{aligned}$$

$$\forall i, j \in \{1, 2, 3\}, \quad X(\omega(E_i)) = X(\omega(E_j)) = 0.$$

So,

$$\begin{aligned} (\nabla_X \tilde{g})(E_i, E_j) &= B(X, E_i)\omega(E_j) + B(X, E_j)\omega(E_i) - \omega(\nabla_X E_i)\omega(E_j) \\ &\quad - \omega(\nabla_X E_j)\omega(E_i). \end{aligned}$$

In particular, we have

- if $i, j \in \{1, 2\}$, we have $\omega(E_i) = \omega(E_j) = 0$, so $(\nabla_X \tilde{g})(E_i, E_j) = 0$. So, $\omega_i^j + \omega_j^i = 0$ and $\omega_j^j = 0$.

- if $i \in \{1, 2\}$ and $j = 3$, we have $\omega(E_j) = 1, \omega(E_i) = 0$ and $B(X, E_j) = 0$. In this case, $(\nabla_X \tilde{g})(E_i, E_j) = B(X, E_i) - \omega(\nabla_X E_i)$.

$$\text{But } \nabla_X \xi = \sum_j \omega_3^j(X)E_j \text{ et } \nabla_X E_i = \sum_j \omega_i^j(X)E_j.$$

So,

$$\begin{aligned} \omega(\nabla_X \xi) &= \sum_j \omega_3^j(X)\omega(E_j) \\ &= \omega_3^3(X)\omega(\xi) \text{ car } \forall j \in \{1, 2\}, \omega(E_j) = 0 \\ &= \omega_3^3(X) \text{ because } \omega(\xi) = 1 \\ &= \tilde{g}(\nabla_X \xi, \xi) \\ &= \tilde{g}(-A_\xi^* X - \tau(X)\xi, \xi) \\ &= -\tau(X). \end{aligned}$$

In the same way, we show

$$\omega(\nabla_X E_i) = C(X, E_i), \quad \forall i \in \{1, 2\}.$$

$$\text{So, } (\nabla_X \tilde{g})(E_i, E_j) = B(X, E_i) - C(X, E_i).$$

- if $i = j = 3$, we have $\omega(E_i) = \omega(E_j) = 1$ et $B(X, E_i) = 0$.
therefore, $(\nabla_X \tilde{g})(E_i, E_j) = -2\omega(\nabla_X E_3) = -2\tau(X)$.

Hence i).

- ii) For all $i, j, k \in \{1, 2, 3\}$, we have:

$$d\omega^i(E_j, E_k) = E_j(\omega^i(E_k)) - E_k(\omega^i(E_j)) - \omega^i([E_j, E_k]).$$

$$E_j(\omega^i(E_k)) = E_j(\tilde{g}(E_i, E_k)) = E_j(g(E_i, E_k) + \omega(E_i)\omega(E_k)) = 0.$$

Similarly, we have $E_k(\omega^i(E_j)) = 0$.

Then,

$$\begin{aligned} d\omega^i(E_j, E_k) &= -\omega^i([E_j, E_k]) \\ &= -\tilde{g}(E_i, [E_j, E_k]) \\ &= \tilde{g}(E_i, \nabla_{E_k} E_j) - \tilde{g}(E_i, \nabla_{E_j} E_k) \\ &= g(E_i, \nabla_{E_k} E_j) - g(E_i, \nabla_{E_j} E_k) + \omega(E_i)\{\omega(\nabla_{E_k} E_j) - \omega(\nabla_{E_j} E_k)\}. \end{aligned}$$

But $\nabla_{E_k} E_j = \sum_t \omega_j^t(E_k) E_t$, so

$$\begin{aligned} \omega(\nabla_{E_k} E_j) &= \sum_t \omega_j^t(E_k) \omega(E_t) \\ &= \omega_j^3(E_k) \quad \text{because } \omega(E_1) = \omega(E_2) = 0. \end{aligned}$$

Similarly $\omega(\nabla_{E_j} E_k) = \omega_k^3(E_j)$.

So

$$d\omega^i(E_j, E_k) = g(E_i, \nabla_{E_k} E_j) - g(E_i, \nabla_{E_j} E_k) + \omega(E_i)\{\omega_j^3(E_k) - \omega_k^3(E_j)\}.$$

Hence ii).

- iii) For all $i, j, k, l \in \{1, 2, 3\}$, we have:

$$d\omega_i^j(E_k, E_l) = E_k(\omega_i^j(E_l)) - E_l(\omega_i^j(E_k)) - \omega_i^j([E_k, E_l]).$$

with

$$\begin{aligned} \omega_i^j(E_l) &= \tilde{g}(\nabla_{E_l} E_i, E_j) \\ &= g(\nabla_{E_l} E_i, E_j) + \omega(\nabla_{E_l} E_i)\omega(E_j) \\ \Rightarrow E_k(\omega_i^j(E_l)) &= E_k(g(\nabla_{E_l} E_i, E_j)) + E_k(\omega(\nabla_{E_l} E_i)\omega(E_j)). \end{aligned}$$

Similarly

$$E_l(\omega_i^j(E_k)) = E_l(g(\nabla_{E_k} E_i, E_j)) + E_l(\omega(\nabla_{E_k} E_i)\omega(E_j)).$$

$$E_k(g(\nabla_{E_l} E_i, E_j)) = (\nabla_{E_k} g)(\nabla_{E_l} E_i, E_j) + g(\nabla_{E_k} \nabla_{E_l} E_i, E_j) + g(\nabla_{E_l} E_i, \nabla_{E_k} E_j).$$

$$E_l(g(\nabla_{E_k} E_i, E_j)) = (\nabla_{E_l} g)(\nabla_{E_k} E_i, E_j) + g(\nabla_{E_l} \nabla_{E_k} E_i, E_j) + g(\nabla_{E_k} E_i, \nabla_{E_l} E_j).$$

$$\omega_i^j([E_k, E_l]) = g(\nabla_{[E_k, E_l]} E_i, E_j) + \omega(\nabla_{[E_k, E_l]} E_i)\omega(E_j).$$

$$E_k(\omega(\nabla_{E_l} E_i)\omega(E_j)) = E_k(\omega(\nabla_{E_l} E_i))\omega(E_j).$$

$$E_l(\omega(\nabla_{E_k} E_i)\omega(E_j)) = E_l(\omega(\nabla_{E_k} E_i))\omega(E_j).$$

Then

$$\begin{aligned} d\omega_i^j(E_k, E_l) &= (\nabla_{E_k} g)(\nabla_{E_l} E_i, E_j) + g(\nabla_{E_k} \nabla_{E_l} E_i, E_j) + g(\nabla_{E_l} E_i, \nabla_{E_k} E_j) \\ &\quad + E_k(\omega(\nabla_{E_l} E_i))\omega(E_j) - (\nabla_{E_l} g)(\nabla_{E_k} E_i, E_j) - g(\nabla_{E_l} \nabla_{E_k} E_i, E_j) \\ &\quad - g(\nabla_{E_k} E_i, \nabla_{E_l} E_j) - E_l(\omega(\nabla_{E_k} E_i))\omega(E_j) - g(\nabla_{[E_k, E_l]} E_i, E_j) \\ &\quad - \omega(\nabla_{[E_k, E_l]} E_i)\omega(E_j). \end{aligned}$$

$$\begin{aligned} d\omega_i^j(E_k, E_l) &= (\nabla_{E_k} g)(\nabla_{E_l} E_i, E_j) - (\nabla_{E_l} g)(\nabla_{E_k} E_i, E_j) \\ &\quad + g(\nabla_{E_k} \nabla_{E_l} E_i - \nabla_{E_l} \nabla_{E_k} E_i - \nabla_{[E_k, E_l]} E_i, E_j) \\ &\quad + g(\nabla_{E_l} E_i, \nabla_{E_k} E_j) - g(\nabla_{E_k} E_i, \nabla_{E_l} E_j) + E_k(\omega(\nabla_{E_l} E_i))\omega(E_j) \\ &\quad - E_l(\omega(\nabla_{E_k} E_i))\omega(E_j) - \omega(\nabla_{[E_k, E_l]} E_i)\omega(E_j). \end{aligned}$$

$$\begin{aligned} d\omega_i^j(E_k, E_l) &= (\nabla_{E_k} g)(\nabla_{E_l} E_i, E_j) - (\nabla_{E_l} g)(\nabla_{E_k} E_i, E_j) \\ &\quad + g(R(E_k, E_l)E_i, E_j) + g(\nabla_{E_l} E_i, \nabla_{E_k} E_j) - g(\nabla_{E_k} E_i, \nabla_{E_l} E_j) \\ &\quad + \{E_k(\omega(\nabla_{E_l} E_i)) - E_l(\omega(\nabla_{E_k} E_i)) - \omega(\nabla_{[E_k, E_l]} E_i)\}\omega(E_j). \end{aligned}$$

By Gauss-Codazzi equations, we have:

$$\begin{aligned} 0 &= g(\bar{R}(E_k, E_l)E_i, E_j) = g(R(E_k, E_l)E_i, E_j) + B(E_k, E_i)g(A_N E_l, E_j) \\ &\quad - B(E_l, E_i)g(A_N E_k, E_j). \end{aligned}$$

$$\Rightarrow g(R(E_k, E_l)E_i, E_j) = B(E_l, E_i)g(A_N E_k, E_j) - B(E_k, E_i)g(A_N E_l, E_j).$$

But

$$\begin{aligned} (\nabla_{E_k} g)(\nabla_{E_l} E_i, E_j) &= B(E_k, \nabla_{E_l} E_i)\omega(E_j) + B(E_k, E_j)\omega(\nabla_{E_l} E_i). \\ (\nabla_{E_l} g)(\nabla_{E_k} E_i, E_j) &= B(E_l, \nabla_{E_k} E_i)\omega(E_j) + B(E_l, E_j)\omega(\nabla_{E_k} E_i). \end{aligned}$$

$$\begin{aligned} g(\nabla_{E_l} E_i, \nabla_{E_k} E_j) - g(\nabla_{E_k} E_i, \nabla_{E_l} E_j) &= \sum_t \{\omega_i^t(E_l)\omega_j^t(E_k) - \omega_i^t(E_k)\omega_j^t(E_l)\} \\ &= - \sum_t \omega_i^t \wedge \omega_j^t(E_k, E_l). \end{aligned}$$

Since

$$\omega(\nabla_{E_k} E_i) = \omega_i^3(E_k), \quad \omega(\nabla_{E_l} E_i) = \omega_i^3(E_l)$$

and

$$\omega(\nabla_{[E_k, E_l]} E_i) = \omega_i^3([E_k, E_l]),$$

we obtain:

$$\begin{aligned} d\omega_i^j(E_k, E_l) &= B(E_k, \nabla_{E_l} E_i)\omega(E_j) + B(E_k, E_j)\omega_i^3(E_l) - B(E_l, \nabla_{E_k} E_i)\omega(E_j) \\ &\quad - B(E_l, E_j)\omega_i^3(E_k) + B(E_l, E_i)g(A_N E_k, E_j) \\ &\quad - B(E_k, E_i)g(A_N E_l, E_j) - \sum_t \omega_i^t \wedge \omega_j^t(E_k, E_l) \\ &\quad + \{E_k(\omega_i^3(E_k)) - E_l(\omega_i^3(E_k)) - \omega_i^3([E_k, E_l])\}\omega(E_j). \end{aligned}$$

Hence *iii*).

□

Corollary 3.1. *If the lightlike hypersurface M is quasi-conformal screen, in other words $A_N = \varphi A_\xi^* + \psi P$, then we have :*

$$\omega_i^j(X) + \omega_j^i(X) = \begin{cases} 0 & \text{if } i, j \in \{1, 2\} \\ -2\tau(X) & \text{if } i = j = 3 \\ (\varphi - 1)g(A_\xi^* X, E_i) + \psi g(PX, E_i) & \text{if } i \in \{1, 2\} \text{ and } j = 3. \end{cases} \quad (3.4)$$

Since the operator A_ξ^* is diagonalizable, we can take the basis $\{E_i\}_{i=1,2,3}$ as a basis of eigenvectors associated with the eigenvalues of the matrix associated with A_ξ^* i.e, $A_\xi^* E_i = \lambda_i E_i$.

We have,

Corollary 3.2. *By proposition (3.1), we have*

(1)

$$\omega_i^j(X) + \omega_j^i(X) = \begin{cases} 0 & \text{if } i, j \in \{1, 2\} \\ -2\tau(X) & \text{if } i = j = 3 \\ (\varphi - 1)\lambda_i \omega^i(X) & \text{if } i \in \{1, 2\} \text{ and } j = 3. \end{cases}$$

(2)

$$\begin{aligned} d\omega_i^j(E_k, E_l) = & \{\lambda_k \omega_i^k(E_l) - \lambda_l \omega_i^l(E_k) + d\omega_i^3(E_k, E_l)\} \omega(E_j) + \lambda_k \omega_i^3(E_l) \\ & - \lambda_l \omega_i^3(E_k) - \sum_{t=1}^2 \omega_i^t \wedge \omega_j^t(E_k, E_l). \end{aligned}$$

If in addition, the lightlike hypersurface M is quasi-conformal screen, we obtain

$$\omega_i^j(X) + \omega_j^i(X) = \begin{cases} 0 & \text{if } i, j \in \{1, 2\} \\ -2\tau(X) & \text{if } i = j = 3 \\ \{(\varphi - 1)\lambda_i + \psi\} \omega^i(X) & \text{if } i \in \{1, 2\} \text{ and } j = 3. \end{cases}$$

4. NULL MEAN CURVATURE FIELD AND ITS LAPLACIAN OF LIGHTLIKE HYPERSURFACE

Let $(M, g, S(TM))$ be a lightlike hypersurface of Lorentz-Minkowski space $\mathbb{R}_1^4$. The mean curvature of the lightlike hypersurface M , denoted α , is defined by

$$\alpha = \text{tr}(A_\xi^*) \quad (4.1)$$

Thus, with respect to the orthonormal basis $\{E_i\}_{i=1,2}$, we have

$$\alpha = \sum_i \tilde{g}(A_\xi^* E_i, E_i) = \sum_i g(A_\xi^* E_i, E_i) = \sum_i B(E_i, E_i) = \text{tr}(B).$$

4.1. The Laplacian operator Δ . Let $x : M \longrightarrow \mathbb{R}_1^4$ be an isometric immersion. The Laplacian operator is defined by

$$\Delta x = - \sum_i \{ \bar{\nabla}_{E_i} \bar{\nabla}_{E_i} x - \bar{\nabla}_{\nabla_{E_i} E_i} x \}. \quad (4.2)$$

x being a position vector in $\mathbb{R}_1^4$, then $\bar{\nabla}_{E_i}x = E_i$ and $\bar{\nabla}_{\nabla_{E_i}E_i}x = \nabla_{E_i}E_i$. So,

$$\Delta x = - \sum_i \{ \bar{\nabla}_{E_i}E_i - \nabla_{E_i}E_i \}.$$

But $\bar{\nabla}_{E_i}E_i - \nabla_{E_i}E_i = B(E_i, E_i)N$, thus equation (4.2) become

$$\Delta x = - \sum_i B(E_i, E_i)N = -tr(B)N = -\alpha N. \quad (4.3)$$

4.2. Laplacian of the mean curvature field H . We denote by S the shape operator of the hypersurface M and H the mean curvature field, i.e $H = \alpha N$.

Then for any $X \in \Gamma(TM)$, we have $\bar{\nabla}_X H = \bar{\nabla}_X(\alpha N) = X(\alpha)N + \alpha \bar{\nabla}_X N$. But $\bar{\nabla}_X N = -SX + \tau(X)N$, so $\bar{\nabla}_X H = (X(\alpha) + \alpha\tau(X))N - \alpha SX$.

Thus, with respect to the orthonormal basis $\{E_i\}_{i=1,2}$, we obtain the Laplacian of H is given by:

Lemma 4.1.

$$\begin{aligned} \Delta H = & (\Delta\alpha)N + 2S(\nabla\alpha) + \alpha \left\{ \sum_i (\nabla_{E_i}S)(E_i) - \sum_i (\nabla_{E_i}\tau)(E_i) \right\} + \alpha \sum_i B(E_i, SE_i)N \\ & - 2 \sum_i E_i(\alpha)\tau(E_i)N + \alpha \sum_i \{ \tau(E_i)SE_i - \tau^2(E_i)N \}. \end{aligned} \quad (4.4)$$

,

Proof. let $\{E_i\}_{i=1,2}$ the orthonormal basis. We have, $\bar{\nabla}_{E_i}H = (E_i(\alpha) + \alpha\tau(E_i))N - \alpha SE_i$. So,

$$\begin{aligned} \bar{\nabla}_{E_i}\bar{\nabla}_{E_i}H = & (E_iE_i(\alpha) + E_i(\alpha)\tau(E_i) + \alpha E_i(\tau(E_i)))N - E_i(\alpha)SE_i - \alpha \bar{\nabla}_{E_i}SE_i \\ & + (E_i(\alpha) + \alpha\tau(E_i))(-SE_i + \tau(E_i)N) \\ = & (E_iE_i(\alpha) + E_i(\alpha)\tau(E_i) + \alpha E_i(\tau(E_i)))N - E_i(\alpha)SE_i - \alpha \bar{\nabla}_{E_i}SE_i \\ & - E_i(\alpha)SE_i + E_i(\alpha)\tau(E_i)N - \alpha\tau(E_i)SE_i + \alpha\tau^2(E_i)N \\ = & (E_iE_i(\alpha) + E_i(\alpha)\tau(E_i) + \alpha E_i(\tau(E_i)))N - 2E_i(\alpha)SE_i - \alpha \bar{\nabla}_{E_i}SE_i \\ & + E_i(\alpha)\tau(E_i)N - \alpha\tau(E_i)SE_i + \alpha\tau^2(E_i)N. \end{aligned}$$

and

$$\bar{\nabla}_{\nabla_{E_i}E_i}H = (\nabla_{E_i}E_i(\alpha) + \alpha\tau(\nabla_{E_i}E_i))N - \alpha S\nabla_{E_i}E_i.$$

The Laplacian is defined as follows :

$$\begin{aligned}
 \Delta H &= - \sum_i \{ \bar{\nabla}_{E_i} \bar{\nabla}_{E_i} H - \bar{\nabla}_{\nabla_{E_i} E_i} H \} \\
 &= - \sum_i \{ (E_i E_i(\alpha) + E_i(\alpha) \tau(E_i) + \alpha E_i(\tau(E_i))) N - 2E_i(\alpha) S E_i - \alpha \bar{\nabla}_{E_i} S E_i \\
 &\quad + E_i(\alpha) \tau(E_i) N - \alpha \tau(E_i) S E_i + \alpha \tau^2(E_i) N - (\nabla_{E_i} E_i(\alpha) + \alpha \tau(\nabla_{E_i} E_i)) N + \alpha S \nabla_{E_i} E_i \} \\
 &= - \sum_i \{ E_i E_i(\alpha) - \nabla_{E_i} E_i(\alpha) \} N + 2 \sum_i E_i(\alpha) S E_i + \alpha \sum_i (\bar{\nabla}_{E_i} S E_i - S \nabla_{E_i} E_i) \\
 &\quad + \alpha \sum_i \tau(E_i) S E_i + \sum_i \{ -2E_i(\alpha) \tau(E_i) + \alpha (-E_i(\tau(E_i)) - \tau^2(E_i) + \tau(\nabla_{E_i} E_i)) \} N \\
 &= \Delta \alpha N + 2S \left(\sum_i E_i(\alpha) E_i \right) + \alpha \sum_i \tau(E_i) S E_i + \alpha \sum_i (\bar{\nabla}_{E_i} S E_i - S \nabla_{E_i} E_i) \\
 &\quad + \sum_i \{ -2E_i(\alpha) \tau(E_i) + \alpha (-E_i(\tau(E_i)) - \tau^2(E_i) + \tau(\nabla_{E_i} E_i)) \} N \\
 &= \Delta \alpha N + 2S(\nabla \alpha) + \alpha \sum_i \tau(E_i) S E_i + \alpha \sum_i (\nabla_{E_i} S E_i + B(E_i, S E_i) N - S(\nabla_{E_i} E_i)) \\
 &\quad + \sum_i \{ -2E_i(\alpha) \tau(E_i) + \alpha (-E_i(\tau(E_i)) - \tau^2(E_i) + \tau(\nabla_{E_i} E_i)) \} N \\
 &= \Delta \alpha N + 2S(\nabla \alpha) + \alpha \sum_i \tau(E_i) S E_i + \alpha \sum_i \{ \nabla_{E_i} S E_i - S(\nabla_{E_i} E_i) \} + \alpha \sum_i B(E_i, S E_i) N \\
 &\quad + \sum_i \{ -2E_i(\alpha) \tau(E_i) + \alpha (-E_i(\tau(E_i)) - \tau^2(E_i) + \tau(\nabla_{E_i} E_i)) \} N
 \end{aligned}$$

But $\nabla_{E_i} S E_i - S(\nabla_{E_i} E_i) = (\nabla_{E_i} S) E_i$ and $(\nabla_{E_i} \tau)(E_i) = E_i(\tau(E_i)) - \tau(\nabla_{E_i} E_i)$.
Hence the result. $\square$

Corollary 4.1. *If $(M, S(TM), g)$ is quasi-conformal screen then we have*

$$\begin{aligned}
 (\nabla_{E_i} S)(E_i) &= \nabla_{E_i} (S E_i) - S(\nabla_{E_i} E_i) \\
 &= \nabla_{E_i} (\varphi \overset{*}{A}_\xi E_i + \psi E_i) - [\varphi \overset{*}{A}_\xi + \psi P](\nabla_{E_i} E_i) \\
 &= \nabla_{E_i} (\varphi \overset{*}{A}_\xi E_i) + \nabla_{E_i} (\psi E_i) - \varphi \overset{*}{A}_\xi (\nabla_{E_i} E_i) - \psi (\nabla_{E_i} E_i) \\
 &= E_i(\varphi) \overset{*}{A}_\xi E_i + E_i(\psi) E_i + \varphi (\nabla_{E_i} \overset{*}{A}_\xi)(E_i).
 \end{aligned}$$

Moreover, if the operator $\overset{*}{A}_\xi$ is parallel, and the functions φ and ψ are constant, we have

$$\Delta H = (\Delta \alpha) N + \varphi \sum_i B(E_i, \overset{*}{A}_\xi E_i) H + \alpha \psi H + 2\{ \varphi \overset{*}{A}_\xi (\nabla \alpha) + \psi (\nabla \alpha) \}.$$

Remark 4.1. *If $(M, S(TM), g)$ is conformal screen (i.e. $\psi = 0$), we have*

$$\Delta H = (\Delta \alpha) N + \varphi \sum_i B(E_i, \overset{*}{A}_\xi E_i) H + 2\varphi \overset{*}{A}_\xi (\nabla \alpha).$$

4.3. Lightlike hypersurfaces verifying the equation $\Delta H = \lambda H$.

Theorem 4.1. *Let $(M, g, S(TM))$ be a screen homothetic lightlike hypersurface of Lorentz-Minkowski space $\mathbb{R}_1^4$ such that the shape operator $\overset{*}{A}_\xi$ has the maximal rank 2 and is parallel,*

then the mean curvature vector field H satisfies the equation $\Delta H = \lambda H$ with λ a real constant if and only if the mean curvature α is constant along the screen distribution.

Proof. $\Rightarrow$ Assuming that the mean curvature vector field H satisfies the equation $\Delta H = \lambda H$.

Under the above assumptions, we have

$$\Delta H = (\Delta \alpha)N + \varphi \sum_i B(E_i, A_{\xi}^* E_i)H + 2\varphi A_{\xi}^*(\nabla \alpha). \quad (4.5)$$

Thus $\Delta H = \lambda H$ is equivalent to :

$$2\varphi A_{\xi}^*(\nabla \alpha) = 0, \quad (4.6)$$

and

$$\frac{1}{\alpha} \Delta \alpha + \varphi \sum_i B(E_i, A_{\xi}^* E_i) = \lambda. \quad (4.7)$$

By (4.6) we have $A_{\xi}^*(\nabla \alpha) = 0$, which implies the existence of a smooth function γ such that $\nabla \alpha = \gamma \xi$. With respect to the orthonormal basis E of the screen, we have $\nabla \alpha = E_1(\alpha)E_1 + E_2(\alpha)E_2$, so $\nabla \alpha = \gamma \xi$ is equivalent to $E_1(\alpha)E_1 + E_2(\alpha)E_2 = \gamma \xi$ and this implies that $E_1(\alpha) = E_2(\alpha) = \gamma = 0$, because (E_1, E_2, ξ) forms an orthonormal basis of the hypersurface M .

$E_1(\alpha) = E_2(\alpha) = 0$ implies that the mean curvature α is constant.

$\Leftarrow$ Assuming that the mean curvature α is constant.

Then

$$\Delta H = \varphi \sum_i B(E_i, A_{\xi}^* E_i)H. \quad (4.8)$$

So, $\Delta H = \lambda H \Leftrightarrow \lambda = \varphi \sum_i B(E_i, A_{\xi}^* E_i)$. It only remains to show that λ is constant.

Then we have

$$B(E_i, A_{\xi}^* E_i) = g(A_{\xi}^* E_i, A_{\xi}^* E_i) = g(\lambda_i E_i, \lambda_i E_i) = \lambda_i^2,$$

where λ_i are the eigenvalues of matrix associated to A_{ξ}^* . So, $\lambda = \varphi \sum_i \lambda_i^2$, this implies that λ is constant. $\square$

Example 4.1. Let $\mathbb{R}_1^4$ be the space $\mathbb{R}^4$ endowed with the semi-euclidean metric given by

$$\bar{g}(u, v) = -xx' + yy' + zz' + tt',$$

where $u = (x, y, z, t)$ and $v = (x', y', z', t')$. Let Λ_0^3 the lightlike cone of $\mathbb{R}_1^4$ given by

$$\Lambda_0^3 = \{(x, y, z, t) \in \mathbb{R}_1^4; -x^2 + y^2 + z^2 + t^2 = 0\} \quad (4.9)$$

with $(x, y, z, t) \neq (0, 0, 0, 0)$.

It is shown in [4] that the lightlike cone Λ_0^3 is conformal screen. The radical distribution $\text{Rad}(\Lambda_0^3)$ and screen distribution $ST(\Lambda_0^3)$ are generated respectively by (see [5])

$$\text{Rad}(\Lambda_0^3) = \langle \xi \rangle \quad (4.10)$$

with $\xi = x\partial_x + y\partial_y + z\partial_z + t\partial_t$. And

$$ST(\Lambda_0^3) = \langle E_1, E_2 \rangle \quad (4.11)$$

with

$$E_1 = \left(\frac{t^2 + y^2}{t^2} \right)^{\frac{1}{2}} \left(\partial_y - \frac{y}{t} \partial_t \right)$$

and

$$E_2 = \left(\frac{t^2 + y^2}{x^2} \right)^{\frac{1}{2}} \left(-\frac{yz}{t^2 + y^2} \partial_y - \frac{zt}{t^2 + y^2} \partial_t \right).$$

It is easy to show that (E_1, E_2) is an orthonormal basis of screen distribution.

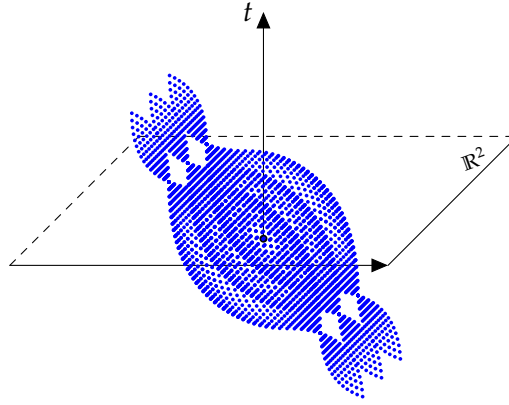


Figure 1. Projection of M in $\mathbb{R}^3$ for $x = -1$, $x = 0$ and $x = 1$

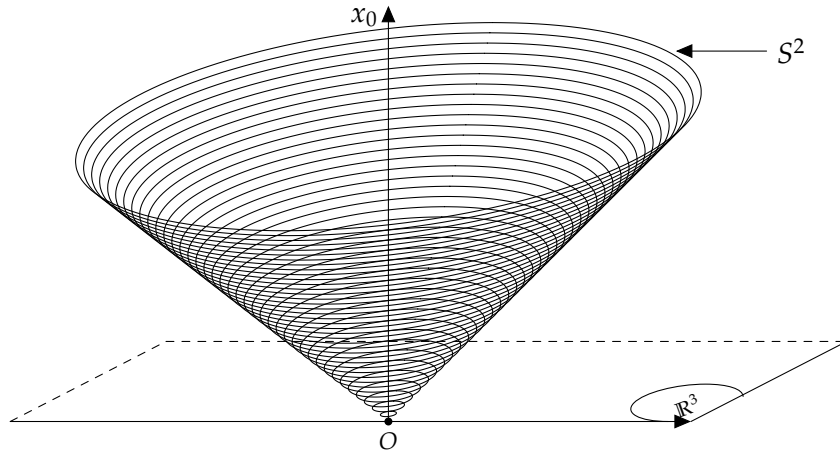


Figure 2. The lightcone Λ_0^3 of $\mathbb{R}_1^4$ is a stacking of spheres $S^2(x_0)$ of $\mathbb{R}^3$

ξ being a position vector in $\mathbb{R}_1^4$, then we have $\overline{\nabla}_{E_i} \xi = \nabla_{E_i} \xi = E_i$, so by Weingarten equation we have $\nabla_{E_i} \xi = -A_{\xi}^* E_i - \tau(E_i) \xi$. Then $A_{\xi}^* E_i - \tau(E_i) \xi = E_i$. So, $A_{\xi}^* E_i = -E_i$ for all $i = 1, 2$ because A_{ξ}^* is $\Gamma(ST(\Lambda_0^3))$ -valued. But $A_{\xi}^* \xi = 0$, so we can give the matrix associated to A_{ξ}^*

relative to the basis $\{E_1, E_2, \xi\}$ by

$$\begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

The mean curvature α_p at point $p = (x, y, z, t)$ is given by $\alpha_p = -2$ and let the mean curvature vector field H of the lightlike cone Λ_0^3 .

By equation (4.4), we have

$$\begin{aligned} \Delta H &= \varphi \sum_i B(E_i, A_{\xi}^* E_i) H \\ &= -\varphi \sum_i B(E_i, E_i) H \\ &= -\varphi \operatorname{tr}(B) H \\ &= 2\varphi H \text{ because } \operatorname{tr}(B) = \alpha_p = -2. \end{aligned}$$

Thus the mean curvature vector field H satisfies the equation $\Delta H = \lambda H$ with $\lambda = 2\varphi$.

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