



A GENERALIZATION OF IONESCU-WEITZENBÖCK'S INEQUALITY, USING HUYGENS-STEINER'S THEOREM FROM MECHANICS

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ABSTRACT. The purpose of this note is to give a new proof of a known generalization of Ionescu-Weitzenböck's inequality, using Huygens-Steiner's theorem from mechanics. This will show an unexpected link between rigid body dynamics and triangle geometry.

1. HUYGENS-STEINER'S THEOREM FROM MECHANICS

Huygens-Steiner's theorem ([6]) expresses the moment of inertia as a quadratic function. **Huygens-Steiner's theorem.** Let A_1, \dots, A_N be N points and m_1, \dots, m_N be N numbers. Let us define the moment of inertia function about a point M , in the following way:

$$F(M) = \sum_{k=1}^N m_k A_k M^2.$$

Then we have, for all Ω, M ,

$$F(M) = F(\Omega) - 2 \left(\sum_{k=1}^N m_k \overrightarrow{\Omega A_k} \right) \cdot \overrightarrow{\Omega M} + \left(\sum_{k=1}^N m_k \right) \Omega M^2.$$

This theorem just follows from the identity

$$A_k M^2 = \|\overrightarrow{A_k \Omega} + \overrightarrow{\Omega M}\|^2 = A_k \Omega^2 + 2 \overrightarrow{A_k \Omega} \cdot \overrightarrow{\Omega M} + \Omega M^2.$$

In mechanics, the m_k are positive masses. So their sum is non-zero. Thus, we can choose the center of inertia as Ω :

$$\Omega = O + \frac{1}{\sum_{k=1}^N m_k} \sum_{k=1}^N m_k \overrightarrow{O A_k}.$$

This definition does not depend on the origin O . Taking $O = \Omega$, we obtain

$$\sum_{k=1}^N m_k \overrightarrow{\Omega A_k} = \vec{0}.$$

2010 *Mathematics Subject Classification.* 51M16; 70B10.

Key words and phrases. Ionescu-Weitzenböck's inequality, Huygens-Steiner's theorem, parallel axis theorem, center of inertia, moment of inertia, rigid body dynamics, triangle geometry.

This gives us a simpler form of Huygens-Steiner's theorem:

$$F(M) = F(\Omega) + \left(\sum_{k=1}^N m_k \right) \Omega M^2.$$

In dimension 3, we can obtain a variant of this theorem called the parallel axis theorem, by replacing the center of inertia Ω with a line passing through Ω , the point M with a line parallel to Ω , the distance $A_k\Omega$ with the distance between the point A_k and the line Ω , the distance A_kM with the distance between the point A_k and the line M , the distance ΩM with the distance between the line Ω and the line M .

2. A GENERALIZATION OF IONESCU-WEITZENBÖCK'S INEQUALITY

Here, we will take fictitious positive and negative masses m_k whose sum is 0. In this case, the vector of inertia

$$\vec{U} = \sum_{k=1}^N m_k \overrightarrow{OA_k}$$

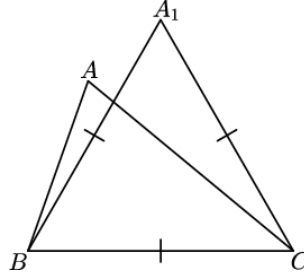
does not depend on the origin O , and we obtain another simpler form of Huygens-Steiner's theorem:

$$F(M) = F(\Omega) - 2\vec{U} \cdot \overrightarrow{\Omega M}.$$

More precisely, let us take

$$A_2 = B, A_3 = C, m_1 = 2, m_2 = m_3 = -1, \Omega = B, M = A.$$

As A_1 and O , we can choose the point such that the triangle A_1BC is equilateral, situated on the same side of BC as A (see the figure).



We obtain

$$2A_1A^2 - BA^2 - CA^2 = 2A_1B^2 - BC^2 + 2(\overrightarrow{A_1B} + \overrightarrow{A_1C}) \cdot \overrightarrow{BA},$$

$$2A_1A^2 = BA^2 + CA^2 + BC^2 - 2R \left(2H \frac{\overrightarrow{BC}}{BC} \right) \cdot \overrightarrow{BA},$$

where H is the altitude of the equilateral triangle A_1BC and R is the rotation of angle 90 degrees in the direction $(\overrightarrow{BC}, \overrightarrow{BA})$. Thus,

$$BC^2 + CA^2 + AB^2 = 2\sqrt{3}R(\overrightarrow{BC}) \cdot \overrightarrow{BA} + 2A_1A^2 = 4\sqrt{3}A + 2A_1A^2,$$

where \mathcal{A} is the area of the triangle ABC . This gives us the following theorem:

Theorem. *Let ABC be a triangle with area \mathcal{A} . Let A_1 be the point such that the triangle A_1BC is equilateral, situated on the same side of BC as A . Then we have*

$$BC^2 + CA^2 + AB^2 = 4\sqrt{3}\mathcal{A} + 2A_1A^2.$$

This theorem states that for any constant points B, C , the level curves of $CA^2 + AB^2 - 4\sqrt{3}\mathcal{A}$, seen as a function of A , are the circles with center A_1 . An immediate consequence of this theorem is Ionescu-Weitzenböck's classic inequality:

$$BC^2 + CA^2 + AB^2 \geq 4\sqrt{3}\mathcal{A}.$$

Another proof of this theorem can be found in [4], proofs of other generalizations of Ionescu-Weitzenböck's inequality can be found in [1], [2], [3], [5], and [7] (where another vector argument is used).

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